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SIDDHARTH INSTITUTE OF ENGINEERING & TECHNOLOGY:: PUTTUR
(AUTONOMOUS)

B.Tech IV Year I Semester Regular Examinations November/December-2022

POWER SEMICONDUCTOR DRIVES

(Electrical and Electronics Engineering)

Time: 3 hours

Max. Marks: 60

(Answer all Five Units 5 x 12 = 60 Marks)

UNIT-I

- 1 With neat diagram, explain 1- ϕ fully controlled converter fed by separately excited DC motor in continuous conduction mode. L1 12M

OR

- 2 A 100KW, 440V, 1000 rpm dc motor running at 800rpm and developing 75% rated torque is controlled by a 3- ϕ , 6-pulse Thyristor converter. If the back EMF at rated speed is 410V, determine the triggering angle of the converter. It is fed with a 3- ϕ , 415V, and 50Hz ac supply. L3 12M

UNIT-II

- 3 a Explain the operation of closed loop speed control of dc drive. L2 6M
b A 230V, 870rpm, 100A separately excited DC motor has an armature resistance of 0.02 Ω . It is coupled to an over hauling with a torque of 400N-m. Determine the speed at which motor can hold the Load by regenerative braking. L3 6M

OR

- 4 a Draw and explain operation of torque control by using closed loop control of DC Drives. L2 6M
b Draw and explain operation of current limit control L2 6M

UNIT-III

- 5 Explain the operation of first quadrant chopper fed by separately excited DC motor with necessary waveforms. L1 12M

OR

- 6 a A 230V, 10A, 1500rpm separately excited dc motor with armature resistance of 1.5 Ω motor operates under dynamic braking with chopper control. Braking resistance has a value of 15 Ω .
(i) Calculate the duty ratio of chopper for motor speed of 1200rpm and braking torque equal to 2 times the rated motor torque.
(ii) What will be the motor speed for duty ratio of 0.6 and motor torque equal to twice the rated torque?
b Explain the closed loop speed control of dc motor and show how it can be achieved by a chopper. L5 6M

UNIT-IV

- 7 a Explain voltage control method of Induction motor drive? L2 6M
b A 3- ϕ , 400V, 50Hz, 6 pole star connected induction motor has the following parameters (referred to stator): $R_1=R_2=0.15\Omega$, $X_1=X_2=0.8\Omega$. Determine the initial braking torque if the motor is braked by plugging the full load the slip is 0.04. L4 6M

OR

- 8 Explain briefly voltage source inverter control of induction motor. L2 12M

UNIT-V

- 9 a Explain the operation of self - control of synchronous motor. L2 6M
b Discuss the operation of separate -control of synchronous motor. L2 6M

OR

- 10 Discuss the operation of a voltage source inverter fed synchronous motor in the true synchronous mode. L2 12M

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